

# Temporal Sampling Intervals and Service Frequency Harmonics in Transit Accessibility Evaluation

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## **ABSTRACT**

In the context of public transit networks, repeated calculation of accessibility at multiple departure times provides a more robust representation of local accessibility. However, these calculations can require significant amounts of time and/or computing power. One way to reduce these requirements is to calculate accessibility only for a sample of time points over a time window of interest, rather than every one. To date, many accessibility evaluation project have employed temporal sampling strategies, but the effects of different strategies have not been investigated and their performance has not been compared. Using detailed block-level accessibility calculated at 1-minute intervals as a reference dataset, four different temporal sampling strategies are evaluated. Systematic sampling at a regular interval performs well on average but is susceptible to spatially-clustered harmonic error effects which may bias aggregate accessibility results. A constrained random walk sampling strategy provides slightly worse average sample error, but eliminates the risk of harmonic error effects.

## 1 INTRODUCTION

2 The concept of accessibility has been an active topic of research in fields related to transportation  
3 and land use for many decades (1, 2). Early implementations of accessibility evaluation were  
4 encouraged by rapid advances in computing power in the 1960s and 1970s (3), but were not able to  
5 provide detailed enough results, spatially and/or temporally, for use in many planning applications.  
6 Over the past decade, increased data availability and renewed interest in accessibility metrics have  
7 again encouraged the application of cutting-edge computing approaches to accessibility evaluation.

8 In the context of public transit networks, repeated calculation of accessibility at multiple  
9 departure times provides a more robust representation of local accessibility. However, these calcu-  
10 lations can require significant amounts of time and/or computing power. One way to reduce these  
11 requirements is to calculate accessibility only for a sample of time points over a time window of  
12 interest, rather than every one. Many accessibility research projects already takes this approach.

13 Some benefits of temporal sampling are obvious: an accessibility calculation which is per-  
14 formed for every 5th minute requires only 20% of the computation effort as one which is performed  
15 for every minute. In addition to direct time and cost savings, making accessibility evaluation more  
16 tractable may increase its adoption in early-stage transportation or land use planning projects where  
17 planners benefit from quick feedback. Temporal sampling may also offer an opportunity to im-  
18 prove an accessibility evaluation in other dimensions, such as by increasing the spatial resolution  
19 or lengthening the temporal coverage, while maintaining the same overall project cost. However,  
20 all of these benefits come at the cost of decreased accuracy; additionally, this accuracy loss may not  
21 be distributed evenly over space or time. The goal of this analysis is to begin to identify and quan-  
22 tify those costs so that researchers and practitioners can make informed decisions when selecting  
23 parameters for accessibility evaluation project.

## 24 BACKGROUND

25 Accessibility, as defined by Hansen (1), measures the “opportunity for interaction” between peo-  
26 ple and places. Many specific implementations of accessibility metrics exist; Geurs and van Wee  
27 (4) provide useful categorizations of approaches to measuring accessibility. All accessibility met-  
28 rics depend on measuring, calculating, or modeling the cost of travel, often expressed in terms  
29 of time. Most of the accessibility metrics discussed in this analysis are *location-based* metrics:  
30 they incorporate (sometimes very detailed) calculations of what opportunities can be reach from  
31 a given location at a given time. As an example, a typical accessibility metric might indicate that  
32 if a traveler departs from a specific intersection at 8:10 AM, he could reach 15,000 jobs within 30  
33 minutes.

34 Public transit networks, like all schedule-based transportation systems, have two important  
35 constraints: you can only depart from specific places, and you can only depart at specific times. The  
36 latter is an important consideration when evaluating accessibility of transit systems. Accessibility  
37 calculation relies on travel time calculation, and travel times vary over the course of the day. Thus,  
38 the selection of a departure time, or departure times, impacts the final accessibility metrics. Until  
39 relatively recently, implementations of accessibility measures for public transit typically focused  
40 on single time points, assigning the accessibility achieved at one departure time to a location or  
41 traveler. Some studies expanded this approach to include several time points, typically hourly,  
42 over the course of a day. These approaches are reviewed by Owen and Levinson (5).

43 Since then, Geurs et al. (6) have identified “temporal dynamics in accessibility” as a rapidly-  
44 expanding field, and this is clearly demonstrated in the literature. Owen and Levinson (5) explic-

45 itly compares “continuous accessibility,” calculated for every minute and then averaged over a  
46 time window, to single-departure-time metrics and demonstrates their ability to improve models  
47 of commute mode share. Similarly, Legrain et al. (7) employ accessibility averaged continuously  
48 over time periods for mode share modeling; Farber et al. (8) and Widener and Shannon (9) use  
49 accessibility calculated at every minute of the day to evaluate access to grocery stores.

50 Alternatively, accessibility is evaluated at a sample of time points and then aggregated, typ-  
51 ically by averaging. Karner (10) demonstrates the application of a “highly resolved temporal met-  
52 ric” for transit accessibility in equity evaluation for federal grant programs, averaging 9 temporal  
53 samples selected from 15-minute bins over a two hour period. (This corresponds to the systematic  
54 sampling strategy evaluated below, with  $f = 15$ .) Tasic et al. (11) and Lei et al. (12) employ eval-  
55 uation at multiple time points, but focus on access *to* transit facilities rather than accessibility *using*  
56 transit to reach destinations. Ding et al. (13) expand the temporal dimension of transit accessibility  
57 to cases where use of transit is limited by capacity, investigating how supply and demand for transit  
58 service fluctuate over the day.

59 Notably, none of these studies robustly defend the choice of temporal sampling strategy, or  
60 compare it against other possibilities — yet each required a decision about what specific time points  
61 to use. In many cases, suitability seems to be implied simply because sample points are spread  
62 evenly over time. However, this explicitly violates the principle of probability sampling and may  
63 introduce sampling bias; this risk is higher for time-series datasets that exhibit cyclical patterns  
64 (14) — which, as discussed below, is certainly the case with transit accessibility data [Figure 1](#).

65 In other cases, accessibility is evaluated continuously over time with the implication that  
66 more must be better — but perhaps equally meaningful results could be achieved with less com-  
67 putation effort? The time and computation resources required to implement detailed accessibility  
68 evaluations are rarely discussed, but they can be a significant barrier to implementation. In the *Ac-  
69 cess Across America: Transit 2014* project (15), the calculation of transit accessibility at 120 time  
70 points for 70,759 Census blocks in the Minneapolis–Saint Paul, MN statistical area was executed  
71 in parallel over many powerful computers; if run on a single high-end workstation, it would have  
72 taken approximately 30 hours to complete.

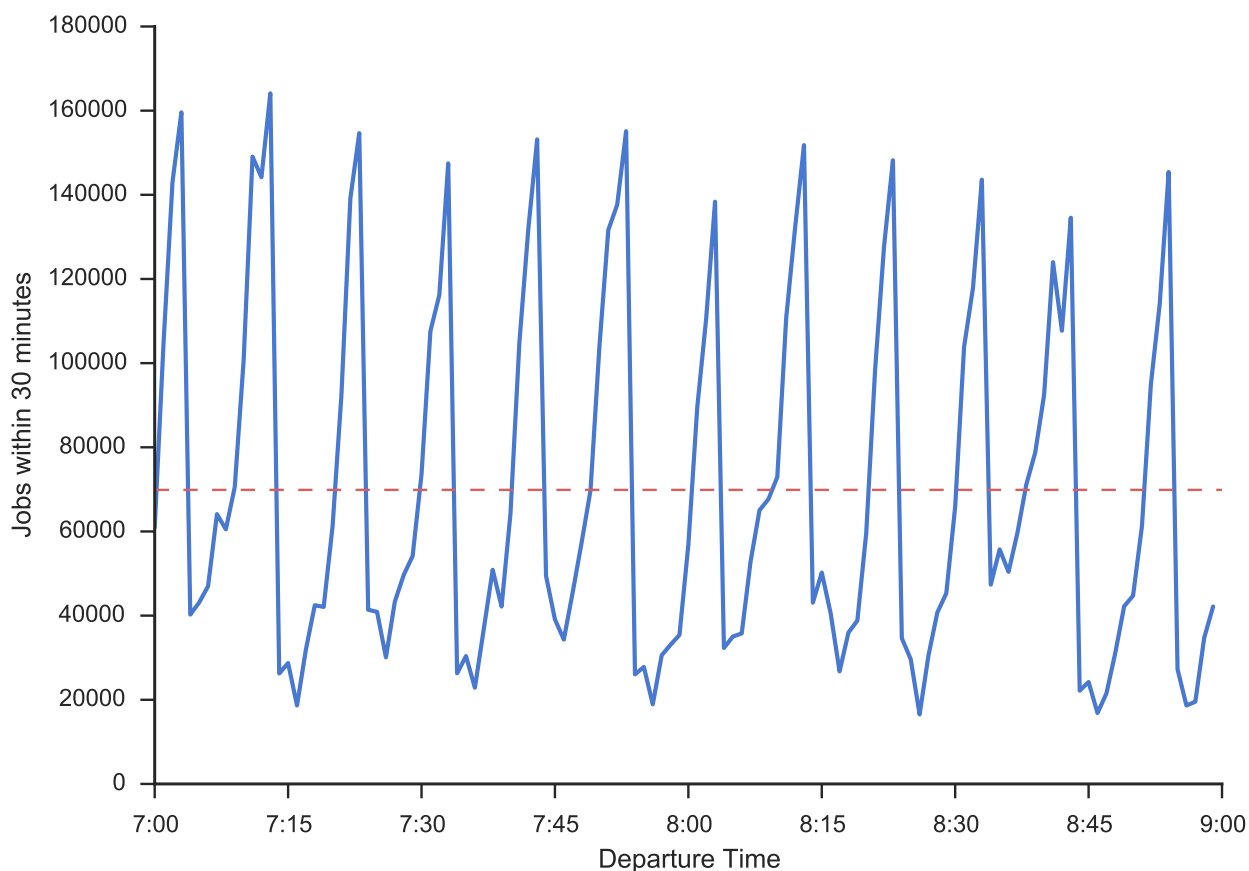
73 This computational complexity is not unreasonable for research projects or analysis pro-  
74 grams undertaken by public agencies. But it is important to recognize that it may limit the impact  
75 that accessibility evaluation can have on transportation and land use planning. It is difficult to  
76 incorporate a calculation which may take many hours into sketch planning, scenario building, or  
77 alternatives analysis because any change to the model network requires an entirely new calcula-  
78 tion. Interactive accessibility evaluation tools which provide a balance of fast enough and precise  
79 enough feedback in response to a network or land use change could dramatically change the way  
80 that planners interact with accessibility concepts. New algorithms for routing on transit networks  
81 (such as RAPTOR (16), already implemented in OpenTripPlanner) can improve response times;  
82 intelligent temporal sampling may also play a role.

## 83 DATA

84 The accessibility data used in this analysis were calculated by the University of Minnesota’s Acces-  
85 sibility Observatory as part of the *Access Across America: Transit 2014* project. For Census blocks  
86 in the Minneapolis–Saint Paul, MN metropolitan area, the data indicate the number of jobs that can  
87 be reached within various time thresholds using a combination of walking and transit. Travel times  
88 are calculated on a combined pedestrian and transit network using transit schedules effective in Jan-

89 uary 2014, and include walking, waiting, and on-vehicle trip components. Job counts and locations  
 90 are based on estimated published by the U.S. Census Bureau. Additional methodological details  
 91 are presented in Owen and Levinson (15). This analysis uses the data for the 30-minute travel time  
 92 threshold, chosen to correspond roughly to the national average commute time of 25 minutes (17).

93 A critical feature of this dataset is that rather than assuming a single fixed departure time,  
 94 the accessibility calculations were repeated for every minute from 7:00 AM to 9:00 AM, for a total  
 95 of 120 accessibility observations at each origin block location. Figure 1 illustrates the data for a  
 96 single block group: the accessibility value for each minute indicates the number of jobs that can be  
 97 reached within 30 minutes if a traveler departs at exactly that time. Accessibility increases as transit  
 98 vehicles approach nearby stops and stations, then drops after trips depart due to the wait the before  
 99 the next trip. This particular block shows a very pronounced cyclical pattern, with accessibility  
 100 peaks occurring every 10 minutes. The location is near a station on Minneapolis' Blue Line LRT  
 101 route, which provides frequent service and a fast connections to downtown.



**FIGURE 1** : Accessibility plot for a single Census block (270531088002012, near the 38th St. Blue Line station in Minneapolis, MN). For each departure time between 7:00 and 9:00 AM, the accessibility value indicates the number of jobs that can be reached within 30 minutes by walking and transit. The dashed horizontal line indicates the average accessibility value over the entire time period.

103 Bureau, which includes those core cities plus many surrounding counties in Minnesota and Wis-  
104 consin. However, some of the suburban and most of the rural parts of this area are not served by  
105 a fixed-route transit system. From these locations, transit service has no impact on accessibility —  
106 the entire 30-minute time budget is consumed without ever reaching a stop or station. Therefore  
107 accessibility to jobs in these places, as represented in this dataset, is determined entirely by walking.

## 108 **METHODOLOGY**

109 Four sampling strategies are evaluated: systematic sampling, simple random sampling, hybrid sys-  
110 tematic/random sampling, and random walk sampling. Because all of these sampling strategies  
111 contain a random element, each is repeated multiple times in a Monte Carlo approach and the re-  
112 sults are averaged to provide an indicator of the overall performance of that strategy. In a single  
113 application of a sampling strategy, a specific sample pattern is generated and used to select, without  
114 replacement, a specified number of data points from the 7:00 AM – 9:00 AM accessibility data for  
115 a block. The sample average is compared to the data average as an indicator of sample error. The  
116 following sections describe each sampling strategy, and the performance evaluation methodology,  
117 in more detail.

### 118 **Sampling Frequency**

119 Each of the temporal sampling strategies explored in this analysis involves some variation on the  
120 concept of sampling frequency, which is expressed differently in each of the strategies. “Fre-  
121 quency” implies some degree of regularity, but the actual regularity of generated samples varies  
122 widely over these strategies. At the most fundamental level, the sampling frequency indicates the  
123 number of samples that will be selected from a window of time points: for a sampling frequency  $f$ ,  
124  $\lfloor T/f \rfloor$  out of  $T$  total time point will be selected. Each of the sampling strategies described below  
125 is evaluated at sampling frequencies of 2 through 10 minutes.

### 126 **Simple Random Sampling**

127 This sampling strategy is the most straightforward: a specified number of sample times are selected  
128 at random, without replacement, from the time window. Because the selection is completely ran-  
129 dom, this strategy will often produce sampling patterns which are very unevenly distributed — a  
130 sample consisting of the first  $f$  time points is just as likely as  $f$  points evenly distributed over the  
131 time window.

### 132 **Systematic Sampling**

133 This sampling strategy involves selecting samples at a regular interval, defined by  $f$ , over the  
134 time window. To avoid bias and give each data point an equal chance of being selected, the first  
135 sample in the sequence is selected randomly from the first  $f$  time points. Thus, one application  
136 of this sampling strategy for  $f = 5$  might produce the sequence 7:00, 7:05, 7:10, etc. while the  
137 next produces 7:03, 7:08, 7:13, etc. This strategy has the advantage that it is guaranteed to produce  
138 evenly-distributed samples. A disadvantage is that if the data itself is cyclical on a frequency which  
139 is a multiple of  $f$ , this strategy may produce a sample pattern which coincides only with peaks (or  
140 troughs), in which case the sample average could be significantly higher (or lower) than the data  
141 average.

### 142 **Hybrid Sampling**

143 This strategy begins with a systematic sample, starting with the first and selecting every  $f$ th sample  
144 thereafter. Next, a random offset based on the sampling frequency is applied to each sample point.  
145 This can also be regarded as a clustered sampling strategy, where sample candidates are clustered  
146 into bins with a width of  $f$  and then a single random sample point is chosen from each cluster.

147 The motivation behind this strategy is to avoid the temporal clustering of samples that can  
148 occur in simple random sampling while also avoiding the potential harmonic effects of systematic  
149 sampling. While it does avoid clustering on a large scale, it does not enforce any minimum distance  
150 between sequential samples, with the result that the gap between samples varies from 1 to  $2f$ . In the  
151 (unlikely) worst case, this sampling strategy might produce a sample pattern consisting of  $\frac{1}{2} \lfloor T/f \rfloor$   
152 pairs of adjacent samples, with a distance of  $2f$  between each pair. Because adjacent sample points  
153 are likely to have similar values, the sample error in this worst case has the potential to be similar  
154 to systematic sampling at half the frequency.

### 155 **Constrained Random Walk Sampling**

156 This sampling strategy is based on a random walk, where each sample point is a random distance  
157 from the previous. The first sample point is randomly chosen between 1 and  $f$ , and then each  
158 random “next step” is constrained by a function of the sampling frequency, in order to achieve a  
159 mix of randomness and temporal dispersion. To choose each next sample point, a random offset  
160 between  $\lfloor f/2 \rfloor$  and  $\lfloor f + (f/2) \rfloor$  is added to the previous sample point, so that on average the next  
161 sample point is  $f$  greater than the previous.

162 One disadvantage to this sampling method is that it produces sample sets of varying size.  
163 For repeated trials, the average number of samples in each set approaches  $\lfloor T/f \rfloor$ . If a predictable  
164 number of samples is desired (for example to make computation times more predicable), the sample  
165 generation process can be filtered to discard sample patterns which do not contain exactly  $\lfloor T/f \rfloor$   
166 sample points.

### 167 **Comparison of Sampling Strategies**

168 Because the “ground truth” data are available in this analysis, each sampling outcome can be com-  
169 pared directly against the actual distribution, either by calculating the expected sampling outcome  
170 empirically or by estimating it using a Monte Carlo method. The simple random sampling, hybrid  
171 sampling, and random walk sampling strategies each incorporate a high degree of randomness and  
172 can produce extremely large numbers of specific sampling patterns. For example, simple random  
173 sampling of 24 data points from a population of 120 (a 10-minute sampling frequency) can produce  
174 over  $10^{25}$  individual sampling patterns. Therefore, these sampling strategies are evaluated using a  
175 Monte Carlo method where the results of repeated samplings are averaged to estimate the expected  
176 outcome. In this analysis, each of these sampling strategies is repeated 1,000 times for each block  
177 and then averaged; this is repeated for each sampling frequency.

178 The systematic sampling strategy, on the other hand, produces far fewer specific sampling  
179 patterns – for example 10 in the case of a 10-minute sampling frequency. Therefore it is feasible  
180 to calculate the result of all possible sampling outcomes at all sampling frequencies, and compare  
181 the averages to the actual distribution.

182 The performance of the various sampling strategy and frequency combinations are evalu-  
183 ated based on how well they estimate the true average accessibility value for each block. A normal-  
184 ized root mean square error (NRMSE) metric is calculated within the context of each block, where

185 the average accessibility estimated over repeated trials of each sampling method is compared with  
 186 the true average. To compare aggregate performance over many blocks with different accessibility  
 187 scales, each result is normalized using the data range for that block. Thus, the average sampling  
 188 error is expressed as a percentage of the range of the true data for that block (Equation 1).

$$\text{NRMSE} = \frac{\frac{1}{n} \sqrt{\sum_{t=1}^n (\hat{y}_t - y)^2}}{y_{max} - y_{min}} \quad (1)$$

$\hat{y}_t$  = the average of sample sett

$y$  = actual average

$n$  = total number of sample sets

189 As noted above, the study area contains many blocks where transit service has no impact on  
 190 accessibility because no stops or stations can be reached within the 30-minute travel time budget.  
 191 In these locations, accessibility is constant over time (walking speeds are assumed to not vary  
 192 by time of day), and so the average of every sample, regardless of strategy, will be equal to the  
 193 actual average; the sampling error will always be zero. To avoid diluting the results from blocks  
 194 where transit does have an impact on accessibility, these “transit-less” blocks are excluded from  
 195 the analysis of sampling strategy performance.

## 196 RESULTS AND DISCUSSION

197 Figure 3 and Table 1 present the results for the systematic sampling strategy. The most striking  
 198 feature is the clear harmonic error effects, seen most clearly at the 5- and 10-minute sampling fre-  
 199 quency and to a lesser degree in the 2- and 4-minute sampling frequency. The corridor of high error  
 200 near the center of these maps corresponds to the Blue Line LRT route, which connects the major job  
 201 centers of downtown Minneapolis, the Minneapolis–Saint Paul airport, and the Mall of America.  
 202 During the 7:00 – 9:00 AM weekday morning window used in this evaluation, this route operates  
 203 on a 10-minute frequency, seen clearly in Figure 1. When sampling at a 10-minute frequency, the  
 204 samples often fall on the peaks or troughs of the local accessibility pattern, and therefore produce  
 205 sample averages significantly higher or lower than the data average. When sampling at a 5-minute  
 206 frequency, every other sample hits these peaks or troughs, producing the same effect but to a lesser  
 207 degree. There are corresponding spikes in the standard deviation of the NRMSE at both the 5- and  
 208 10-minute sampling frequencies Table 1, indicating increased dispersion in the sample results.

209 It is interesting to note the performance of the 7-minute sampling frequency with this strat-  
 210 egy. It produces a slightly better mean NRMSE (2.73% vs 2.76%) and a lower standard deviation  
 211 (1.06 vs 1.09) than the 6-minute sampling frequency, despite having fewer sample points. This  
 212 suggests that the 7-minute sampling frequency is not harmonic with the typical service frequency  
 213 of transit routes in the area.

214 The results for the simple random sampling strategy, presented in Figure 4 and Table 2,  
 215 immediately demonstrate the role of increased randomness in sample selection. There are no har-  
 216 monic error effects apparent, and standard deviation of NRMSE at the 5 and 10 minute sampling  
 217 frequencies are significantly lower than for the systematic sampling strategy, indicating more con-  
 218 sistent results. However, the overall performance of this strategy, as indicated by average NRMSE,

**TABLE 1** : Performance of Systematic Sampling Strategy

	Sampling Frequency								
	2	3	4	5	6	7	8	9	10
Median NRMSE	0.58%	1.16%	1.33%	2.24%	2.51%	2.53%	2.85%	3.25%	4.53%
Mean NRMSE	0.70%	1.31%	1.58%	2.61%	2.76%	2.73%	3.07%	3.51%	5.10%
S.D.	0.58	0.79	0.78	1.54	1.19	1.06	1.22	1.27	2.78

**TABLE 2** : Performance of Simple Random Sampling Strategy

	Sampling Frequency								
	2	3	4	5	6	7	8	9	10
Median NRMSE	2.05%	2.90%	3.55%	4.10%	4.58%	5.04%	5.42%	5.88%	6.14%
Mean NRMSE	2.04%	2.89%	3.53%	4.08%	4.56%	5.02%	5.40%	5.85%	6.12%
S.D.	0.50	0.70	0.86	1.00	1.11	1.23	1.32	1.43	1.50

**TABLE 3** : Performance of Hybrid Sampling Strategy

	Sampling Frequency								
	2	3	4	5	6	7	8	9	10
Median NRMSE	1.02%	1.64%	2.19%	2.69%	3.20%	3.66%	4.10%	4.62%	4.91%
Mean NRMSE	1.00%	1.64%	2.21%	2.72%	3.23%	3.71%	4.15%	4.65%	4.96%
S.D.	0.37	0.50	0.61	0.76	0.86	0.96	1.06	1.19	1.29

**TABLE 4** : Performance of Random Walk Sampling Strategy

	Sampling Frequency								
	2	3	4	5	6	7	8	9	10
Median NRMSE	2.58%	1.47%	1.90%	2.41%	2.84%	3.32%	3.70%	4.20%	4.51%
Mean NRMSE	0.70%	1.49%	1.93%	2.45%	2.88%	3.37%	3.76%	4.27%	4.59%
S.D.	0.58	0.34	0.45	0.57	0.67	0.81	0.91	1.07	1.14

219 is markedly worse. It is especially poor at shorter sampling frequencies (2–4), where its average  
220 sample error is over twice that of the the systematic sampling strategy.

221 The hybrid sampling strategy (Figure 5 and Table 3) improves on the performance of the  
222 simple random sampling strategy in both average error and standard deviation of error, while also  
223 avoiding harmonic error effects at the 5- and 10-minute sampling frequencies. The random walk  
224 sampling strategy (Figure 6 and Table 3) provides a similar further improvement. However, at non-  
225 harmonic sampling frequencies the systematic sampling strategy provides a lower average sample  
226 error (but a greater standard deviation) than either the hybrid or the random walk strategy.

227 Figure 2 summarizes the relative performance of all sampling strategies and frequencies.  
228 This chart clearly illustrates the variability in sample error at the 5- and 10-minute sampling fre-  
229 quencies when using the systematic sampling method. Overall, the random walk sampling strategy  
230 provides the best performance, as measured by average sample error and standard deviation of  
231 sample error, while also avoiding harmonic error effects. The systematic sampling method often  
232 performs very well, but appears to be strongly influenced by harmonic error effects that make its  
233 performance unpredictable.

## 234 CONCLUSION

235 It is clear that the selection of a temporal sampling strategy can have a significant impact on the  
236 results of accessibility evaluation, particularly if the chosen strategy does not avoid harmonic error  
237 interactions with the local transit network. Of the strategies compared in this analysis, a constrained  
238 random walk approach provided the best performance, as measured by sample error, while avoiding  
239 harmonic error effects. However, it is important to note that this comparison relied on sample  
240 strategy performance in the context of a single transit network. It is possible that each strategy  
241 could perform better or worse if applied to the transit network in a different city, and additional  
242 research may be useful in finding a strategy that is generalizable.

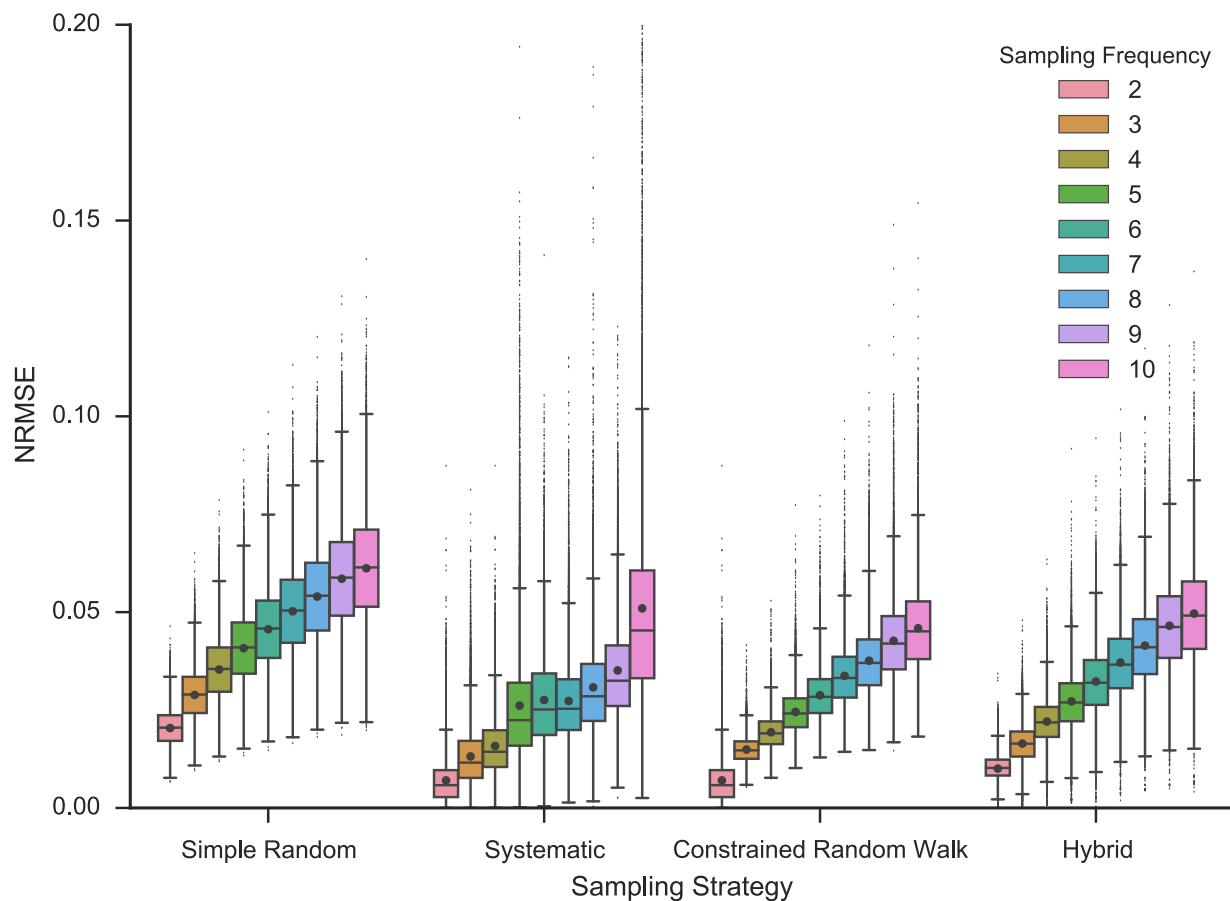
243 It is also clear that a systematic sampling strategy can produce very erratic results compared  
244 to other methods, and that it is susceptible to harmonic error effects due to interactions with the  
245 local transit network. It may be wise to avoid this sampling strategy, particularly in applications  
246 with a goal of analyzing the spatial variation of accessibility. Because harmonic error effects are  
247 associated with nearby transit service, they are inherently clustered spatially and would bias any  
248 spatial analysis efforts. Prime-numbered sampling frequencies (3, 7, 9) may reduce the risk of  
249 harmonic error effects when a systematic sampling strategy is used.

250 It may be interesting to explore sampling approaches which select different strategies and/or  
251 frequencies based on an analysis of the local transit service context. The systematic strategy gives  
252 the best performance in areas where harmonic error effects are not a concern; with minimal pre-  
253 processing of transit schedule data it may be possible to identify areas which are better suited to a  
254 particular sampling strategy or which would benefit from higher sampling rates.

255 Temporal sampling strategies provide an attractive trade-off: an accessibility evaluation  
256 sampled at a 5-minute frequency requires only 20% of the computing effort as one sampled at every  
257 minute, with an average sample error of only 2.5%. However, sampling strategy and sampling  
258 frequency should be selected with an understanding of how they may influence the spatial patterns  
259 of accessibility results.

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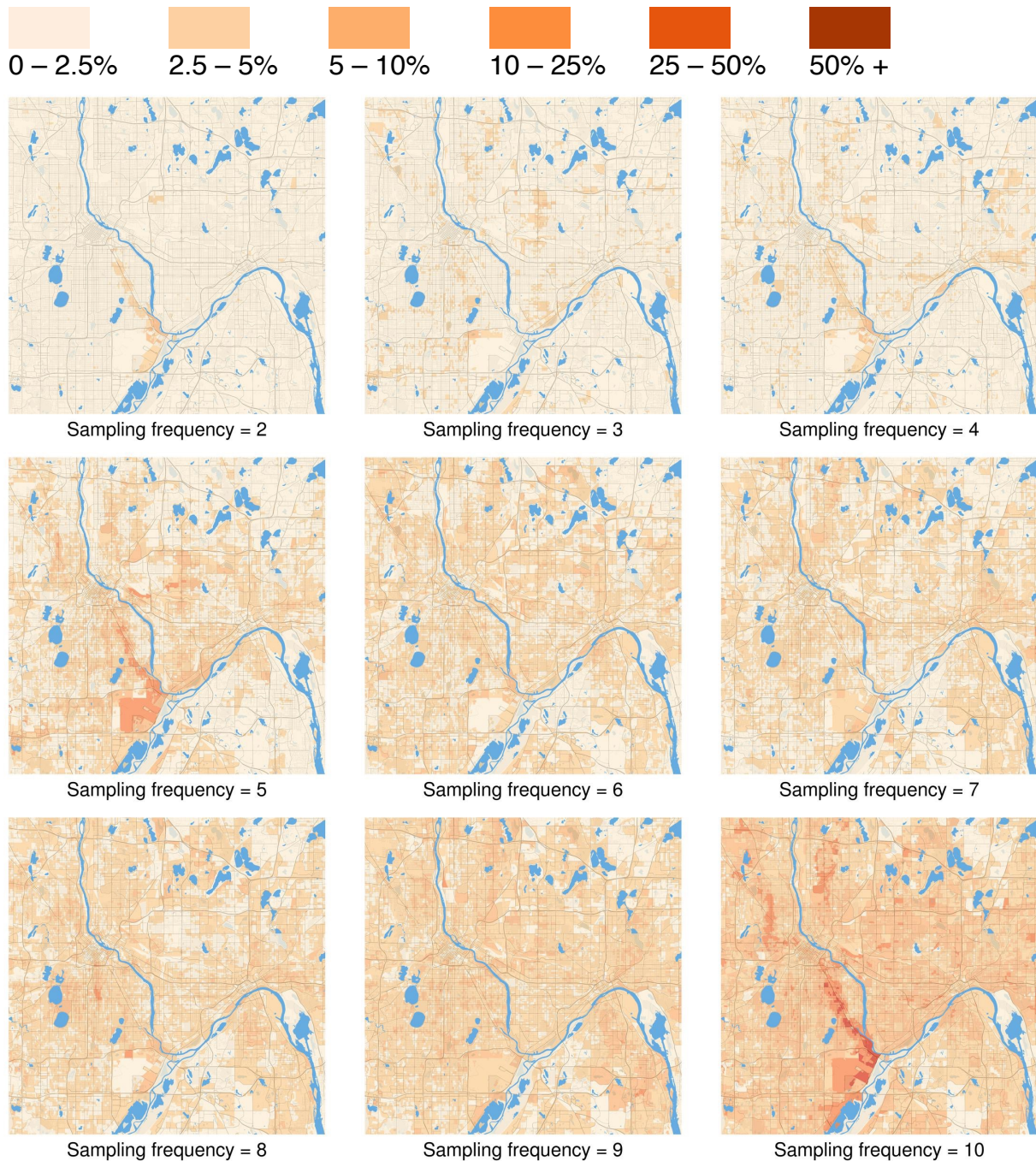
**FIGURE 2** : Box plots for sampling strategy performance over all blocks at each sampling frequency. Boxes show inter-quartile range (25th – 50th percentile) with horizontal medial line; whiskers extend  $1.5 \times \text{IQR}$  above and below. Outliers are plotted individually. Mean is indicated by a dot.

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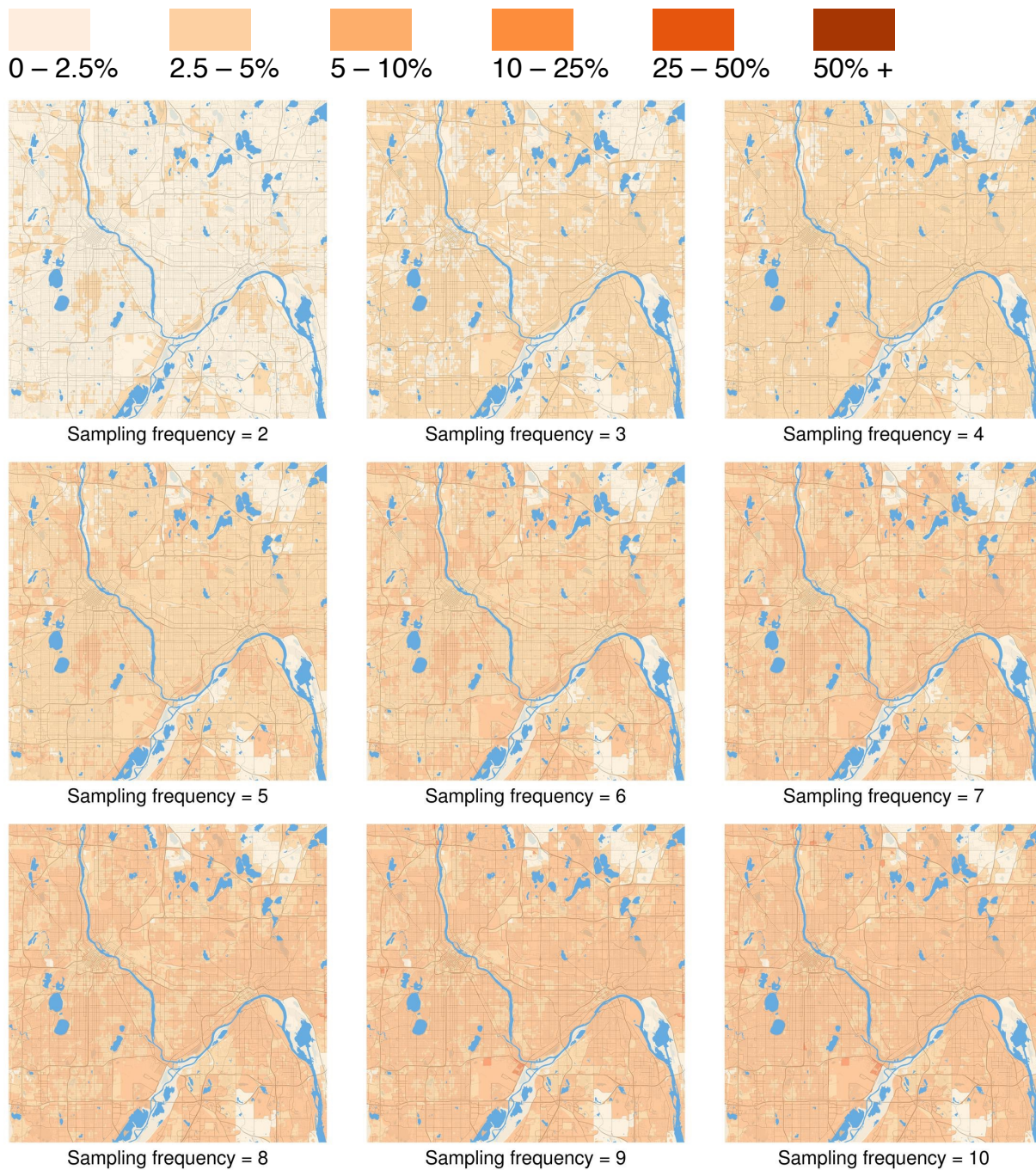
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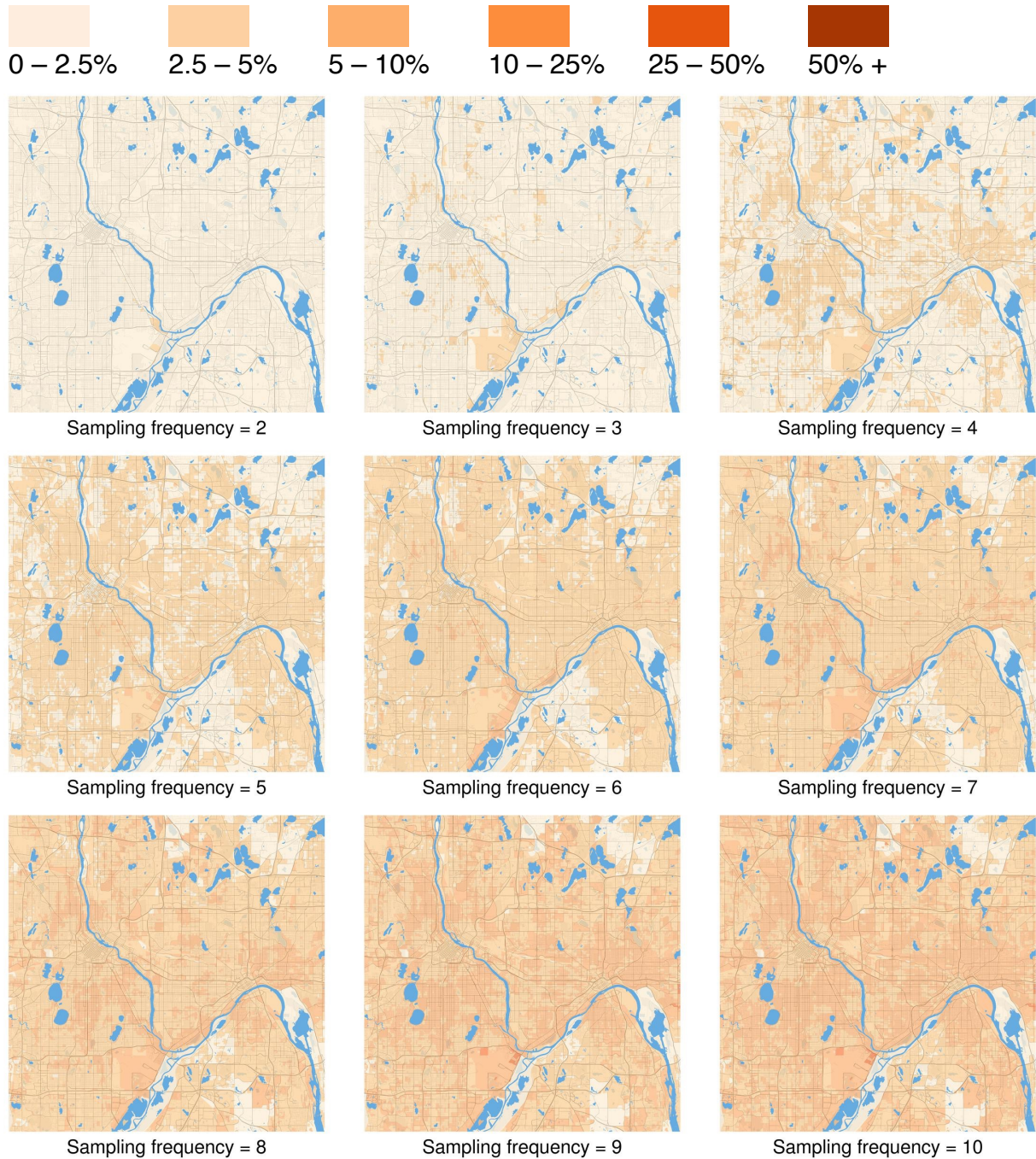
### Average normalized root mean square error



**FIGURE 3** : Maps of block-level performance of the **systematic** sampling strategy, for sampling frequencies of 2 through 10 minutes. Darker colors indicate greater average sample error. Systematic sampling exhibits pronounced harmonic error effects for some sampling frequencies at some locations.

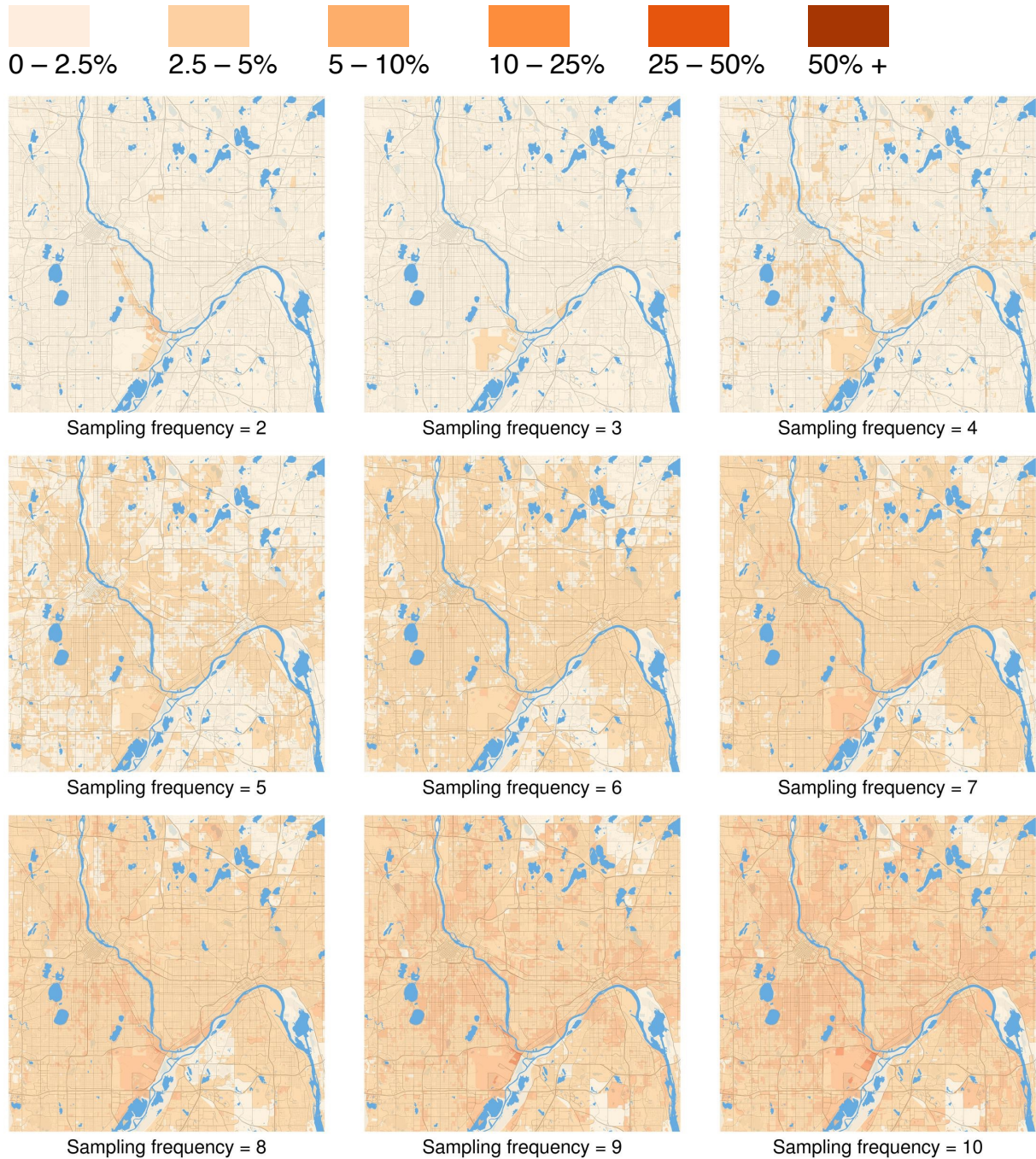
**Average normalized root mean square error**

**FIGURE 4** : Maps of block-level performance of the **simple random** sampling strategy, for sampling frequencies of 2 through 10 minutes. Darker colors indicate greater average sample error.

**Average normalized root mean square error**

**FIGURE 5** : Maps of block-level performance of the **hybrid** sampling strategy, for sampling frequencies of 2 through 10 minutes. Darker colors indicate greater average sample error.

### Average normalized root mean square error



**FIGURE 6 :** Maps of block-level performance of the **random walk** sampling strategy, for sampling frequencies of 2 through 10 minutes. Darker colors indicate greater average sample error.